Indoor Positioning System

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STAT4/510: Basic Consulting Skills

EXECUTIVE SUMMARY

The executive summary contains a brief account of your conclusion, it should be very short and to the point. Write the results not the description of the problem.

Indoor Positioning System

This project exists to design an indoor positioning system (IPS) using data from access points.

We wish to develop this system leveraging data collected from six strategically placed access point within a single floor of a building. The primary aim is to accurately determine the real-time location of devices or individuals within the indoor space facilitating applications such as location-based services or asset tracking.

Summarize conclusions. Don’t put too much background information.

# Background

Rephrase the problem and any relevant issues present. Define any technical terms needed for the paper.

Background of the problem. Discuss other related analyses (information on authors that have addressed similar problems and how they approached solutions)

# Data

# Indoor position systems (IPS) development is an active area of research that can be used in numerous settings. An area of interest is the use of using signal strength from WIFI routers to estimate the location of a device.

The following report, describes and characterizes a large data set compiled in a 15 by 36 meter area that contains the data obtained from a handheld device connected to a WIFI network, in different locations and orientations, in order to create a model to predict indoor positioning.

The data is subdivided in two sub-sets, one denominated offline data, which corresponds to a testing device connected to the network at different locations and orientations, and the other an online data, where 60 locations and orientations of the devices were selected at random.

The offline data, intended to train a model, was collected designing a 1 meter resolution grid, resulting in 166 locations. In each of these locations, the device was oriented starting at 0 degrees inclination and at 45 degrees increments (for a total of 8), and the strength signal measured for each access point was measured 110 times. That is, per each location (x,y) we have 110 samples at each angle, for a total of 880 samples per location, and a total of 1.4608 × 105 observations.

The online data was designed to simulate real-world data (i.e., locations that are not bounded to a grid, and which a device can be oriented at random.) Specifically for the online data, 60 combinations of orientation/locations were randomly selected, and then sampled 110 times, resulting in 6600 measurements in total.

More details of the floor plan, and location of online and offline data can be seen in Figure 1. Circles serve as markers for the positions where offline measurements were conducted, while black squares indicate the locations of the six access points. The positions of the access points were provided in a separate file by the client.

For simplicity, this report will share the results found in the offline data set, but initial process of data cleaning can be directly applied to the online data as well because both sets share the same format.

1

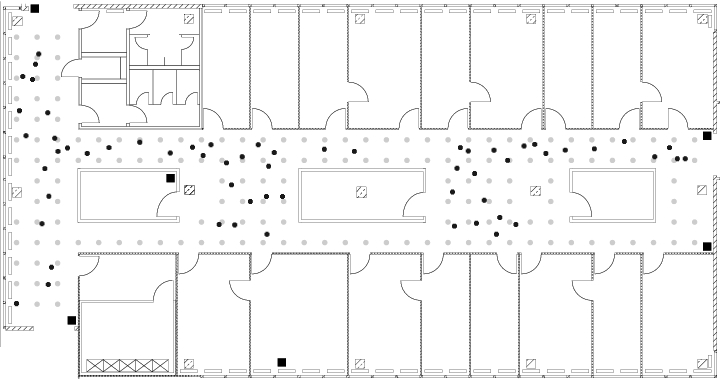


Figure 1: Flooplan location. Access points are squares. Grey dots are offline data locations and black dots are online data locations.

According to documents provided by the client, the data contains the following variables:

• time: time in miliseconds since midnight 01/01/1970 UTC  
• scanMac: IP address of the scanning device, in mm:mm:mm:ss:ss:ss. • pos: the 3-D coordination of the scanning device (x,y,z)  
• orientation: the scanning device’s orientation.  
• mac: the IP address of the access points.  
• signal: signal strength in dBm.  
• channel: the channel frequency.  
• type: type of device (access point = 3, device in adhoc mode =1)

The raw data are stored in a .txt file. The first 3 lines of the data are characterized by the hash (#) symbol, followed by a row that contains all the variables in one line, separated by a semi-colon. A sample of the initial format of the data can be seen below. We start by eliminating the rows that start with the hash symbols from the data set using a strsplit function. The resulting data set contains a total of 146080 rows, and therefore 5312 rows were eliminated. This value, if divided by 3 (first 3 rows contain a hash) is 1770, which is close consistent with the expected number of locations (166) and angles (8). This means that each stack location/orientation combination that contains 110 samples (from herein Location\_orientation stack) was separated by 3 hash symbols.

Some variable names do not correspond to the ones given by the client, for example, orientation is degree in the data set, and the variables type, channel, signal do not have an explicit name. We also note that for pos the x,y,z variables are grouped together, and the mac variable includes signal, channel and type separated by comas. We can then distinguish between single variables (defined by a name and have one value), and secondly composite variables (defined by containing multiple values for one parameter).

We use these patterns to create a matrix with the variables. For this, we created a function that first, separated all the data separated by a semi-colon, a comma, or an equal symbol. Then, we selected the rows corresponding to mac, signal, type and created a matrix that has the information for the specific access point. Lastly, we bind all the information together in a large data frame that contains one row per location/orientation and access point.

Before further exploration and analysis of the data, we conducted converted the variables into the correct types (as defined by the documents provided by the client).

The summary is as follows:

1. 1)  The variables position, orientation, signal and channel were converted to numerical values.
2. 2)  The variable time was converted into a time value using as origin midnight on January 1st, 1970. The original variable was kept in the data set as rawTime in case it becomes necessary for future analysis.
3. 3)  The variable type has binary values of 1 and 3. The documentation explains that type = 3 corresponds to ad-hoc devices, that are not needed for the development and testing of the IPS and therefore, after

removing the rows with a value of type equal to 3, we remove the variable from the data set.

1. 4)  For the exploration, we remove the scanMac, as information given by the client indicates that one

devices was used.

The first rows of the formatted data can be seen in Table 1.

A quick analysis of the numerical data shows that posZ has only zero values (Table 2). This seemingly anomalous value is due to the fact that all of the readings were taken on one floor of the building. We, therefore, removed the posZ variable from the data set. Furthermore, we detect anomalous values for orientation.

# Methods

**K-Nearest Neighbors (KNN) Algorithm**

Your indoor environment is like a canvas with distinct features. Such as Wi-Fi signal strength, and orientation of devices. These features define the nuances of your space, creating a unique fingerprint for each location. Imagine each location as a "friend" in your indoor space. KNN is like asking, "Which locations are most similar to this one?" We consider the proximity of these friends based on the features you've gathered. The algorithm doesn't assume a specific pattern; it adapts to the individual characteristics of your space.

During our comprehensive exploration of various machine learning models to utilize for this project, we carefully considered the KNN because it is a powerful and intuitive method for certain applications. We have discovered challenges that would make this a costly approach for this project though. Some key considerations are the computational demands of KNN, this model involves calculating the distances between data points, which can be computationally demanding especially given the high dimensionality of your data set. KNN tends to degrade as the number of features increases. The “k” part of KNN is how many neighbors we wish to consider in making our prediction, increasing the k value improves accuracy but dramatically drives up the computational costs.

**A diagram of mathematical calculations

Description automatically generated**

This is the technical representation of the K-NN method. This method had underlying assumptions of stationarity, which is to say that the neighboring points are not moving. It also assumes equal importance of features; this algorithm isn’t equipped to deal with particular weights without additional preparation of the features.

**XGBoost**

State the assumptions, explain method

# Results

State the hypotheses

Show the evidence in favor or against the hypotheses

Present testing results and interpret such results

# Conclusions and recommendations

Discuss the broad implications of the project

Use rmodel result to answer the client’s questions and goals of the project

Discuss (i) issues that merit further exploration, (ii) interesting findings that are not part of the client’s questions

Mention reservations about the analyses that may require more complex modeling (due to modeling assumptions not holding, other reasons)

References

Last Name, A. B. (Year). Article Title. Journal Title, Pages #-#. URL. URL.

Last Name, C. D. (Year). Book TitleBook Title URL.

Last Name, D. E., Last Name, F. G. (Year). Report TitleReport Title URL.

Last Name, H. I. (Year, Month Day). Article Title/Headline. Periodical.Periodical.

Organization Name. (Year, Month Day).Webpage Title. URL.

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Tables

Table 1

Table Title

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| --- | --- | --- | --- | --- |
| Column Head | Column Head | Column Head | Column Head | Column Head |
| Row Head | 123 | 123 | 123 | 123 |
| Row Head | 456 | 456 | 456 | 456 |
| Row Head | 789 | 789 | 789 | 789 |
| Row Head | 123 | 123 | 123 | 123 |
| Row Head | 456 | 456 | 456 | 456 |
| Row Head | 789 | 789 | 789 | 789 |

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Figures Title

Figure 1.

Include all figures in their own section, following references, footnotes, and tables. Include a numbered caption for each figure. Use the Table/Figure style for easy spacing between figure and caption.



# Appendix